tetmag – An open-source finite-element software for micromagnetic problems



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Purpose, applications, and background of tetmag

General scientific context

- Micromagnetic theory
- Ferromagnetism on the nanoscale
- Picosecond magnetization dynamics
- Magnetization structures in nano-elements
- Spintronics
- Magnonics

Scientific background

- Internationally renowned team with more than 25 years experience in micromagnetic theory & simulation
- Predecessors of this code were developed at Max-Planck-Institute Halle and Forschungszentrum Jülich
- Software has been used in > 100 high-impact publications
- Numerous predictions of fundamental phenomena with our simulations: spin wave logics (2004), magnetic vortex-core switching (2007), curvature-induced magnetochirality (2010)
- First GPU-accelerated finite-element micromagnetic software
- Finite element method for general geometries (curved or inclined surfaces, complex 3D geometries...)

Publication

First release of tetmag as open-source software in May 2023.

R. Hertel, Rencontre Logiciels Libres, IPCMS 2023



https://github.com/R-Hertel/tetmag

Micromagnetism: Length Scales



Finite Elements for Geometric Flexibility

Advantages of Finite Difference Method	Advantages of Finite Element Method
Relatively easy to implement	Accurate approximation of non-trivial geometries
Low memory requirements per DOF	Adaptive mesh refinement
fast and easy to parallelize	Well suited for three-dimensional nanostructures

Details of the sample shape can have an impact on the magnetic properties. Geometric effects, like curvature-induced asymmetries, require precise geometric models.



Challenges in Modeling: Three-dimensional magnetic nanostructures

Recent development in nanomagnetism : Three-dimensional nanostructures with complex shapes

Functionality, physical properties may depend sensitively on the shape of the nanostructure

Large scale problems with nontrivial geometries

Finite-element simulation with millions of elements

Typical situations in **3D nanomagnetism**

- Large samples of complex shape
- Arrays of interacting particles



Features of tetmag



https://github.com/R-Hertel/tetmag

Features

- General-purpose micromagnetic simulations with LLG + STT
- FEM for geometric flexibility
- Object-oriented C++
- Hybrid FEM-BEM calculation of magnetostatic field calculation
- H2-type matrix compression for efficient BEM integration
- GPU acceleration with CUDA / THRUST
- Platform-independent tested on Linux and MacOS

Can treat any common micromagnetic simulation task:

- Static magnetization structures
- Magnetic switching processes
- Field-driven dynamics
- Current-driven dynamics
- Hysteresis loops



tetmag workflow



tetmag documentation

https://tetmag.readthedocs.io

- Installation guide
- General introduction
- Examples Step-by-step description of simulation studies

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Ex. 3: Current-induced dynamics

When an electric current flows through a ferromagnetic material, it aquires a spin polarization through which the conduction electrons interact with the magnetization. This effect is described by the so-called spin-transfer torque (STT). In this example, we simulate the STT-induced magnetization dynamics in a square Permalloy platelet. The micromagnetic problem simulated here is based on a proposal by Najafi et al., published in Ref. 1.

tetmag.readthedocs.io

The sample is a Permalloy platelet of 100 nm \times 100 nm \times 10 nm size. We use FreeCAD to define the geometry and to generate an irregular FEM mesh with the netgen plugin. In our example, the mesh size is set to 2 nm, resulting in 39 246 irregularly shaped terahedral finite elements.

Calculating the initial configuration

First we simulate the initial configuration – a vortex structure at zero external field and without spin-polarized current. The keyword intial state = vortex_xy can be used to generate a vortex-type initial structure, circulating in the xy plane, from which the magnetization can be relaxed. The simulation.cfg for this static part of the simulation is

name = sp_stt scale = 1.e-9 mesh type = vtk alpha = 1 initial state = vortex_xy time step = 2 # demag refresh interval in ps duration = 5000 # simulation time in ps solver type = gpu torque limit = 1.e-4 remove precession = yes

By performing the static simulation, we quickly obtain the converged state, stored in the file sp_stt.vtu, which we rename to sp_stt_vortex.vtu. This will be the initial state of the

tetmag in action

1. Define geometry and FEM mesh (FreeCAD)



2. Supply input data (ASCII file)

- name = sp4_ scale = 1.e-9 mesh type = vtk alpha = 0.02 initial state = fromfile_sp4_s-state.vtu time step = 0.1 # demag refresh interval in ps duration = 1000 # simulation time in ps solver type = gpu
- external field = 25.0 # Hext in mT theta_H = 90 # polar angle of the field direction in degree phi_H = 170 # azimuthal angle

3. Run the simulation

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	hertel@euclide: ~/Docs/tetmao/example1	
	······································	
t[ps]: 2930.000 tot: 4883.169 de: 302.751 xc: 4580.418 un: 0.000) ze: -0.000 cb: 0.000 sf: 0.000 dm: 0.000 M: 0.00101 0.00199 -0.00360	
t[ps]: 2940.000 tot: 4883.166 de: 302.749 xc: 4580.417 un: 0.000) ze: -0.000 cb: 0.000 sf: 0.000 dm: 0.000 M: 0.00102 0.00197 -0.00360	
t[ps]: 2950.000 tot: 4883.164 de: 302.747 xc: 4580.417 un: 0.000) ze: -0.000 cb: 0.000 sf: 0.000 dm: 0.000 M: 0.00104 0.00194 -0.00360	
t[ps]: 2960.000 tot: 4883.161 de: 302.745 xc: 4580.416 un: 0.000) ze: -0.000 cb: 0.000 sf: 0.000 dm: 0.000 M: 0.00105 0.00191 -0.00360	
t[ps]: 2970.000 tot: 4883.159 de: 302.743 xc: 4580.416 un: 0.000) ze: -0.000 cb: 0.000 sf: 0.000 dm: 0.000 M: 0.00106 0.00189 -0.00360	
t[ps]: 2980.000 tot: 4883.156 de: 302.741 xc: 4580.415 un: 0.000) ze: -0.000 cb: 0.000 sf: 0.000 dm: 0.000 M: 0.00108 0.00186 -0.00360	
t[ps]: 2990.000 tot: 4883.154 de: 302.740 xc: 4580.415 un: 0.000) ze: -0.000 cb: 0.000 sf: 0.000 dm: 0.000 M: 0.00109 0.00184 -0.00360	
t[ps]: 3000.000 tot: 4883.152 de: 302.738 xc: 4580.414 un: 0.000) ze: -0.000 cb: 0.000 sf: 0.000 dm: 0.000 M: 0.00110 0.00181 -0.00360	
t[ps]: 3010.000 tot: 4883.150 de: 302.736 xc: 4580.414 un: 0.000) ze: -0.000 cb: 0.000 sf: 0.000 dm: 0.000 M: 0.00111 0.00179 -0.00360	
t[ps]: 3020.000 tot: 4883.148 de: 302.735 xc: 4580.413 un: 0.000) ze: -0.000 cb: 0.000 sf: 0.000 dm: 0.000 M: 0.00112 0.00176 -0.00360	
t[ps]: 3030.000 tot: 4883.146 de: 302.734 xc: 4580.413 un: 0.000) ze: -0.000 cb: 0.000 sf: 0.000 dm: 0.000 M: 0.00113 0.00174 -0.00360	
t[ps]: 3040.000 tot: 4883.145 de: 302.732 xc: 4580.412 un: 0.000) ze: -0.000 cb: 0.000 sf: 0.000 dm: 0.000 M: 0.00114 0.00172 -0.00360	
t[ps]: 3050.000 tot: 4883.143 de: 302.731 xc: 4580.412 un: 0.000) ze: -0.000 cb: 0.000 sf: 0.000 dm: 0.000 M: 0.00115 0.00169 -0.00360	
t[ps]: 3060.000 tot: 4883.141 de: 302.730 xc: 4580.412 un: 0.000) ze: -0.000 cb: 0.000 sf: 0.000 dm: 0.000 M: 0.00116 0.00167 -0.00360	
t[ps]: 3070.000 tot: 4883.140 de: 302.729 xc: 4580.411 un: 0.000) ze: -0.000 cb: 0.000 sf: 0.000 dm: 0.000 M: 0.00116 0.00165 -0.00360	
t[ps]: 3080.000 tot: 4883.138 de: 302.728 xc: 4580.411 un: 0.000) ze: -0.000 cb: 0.000 sf: 0.000 dm: 0.000 M: 0.00117 0.00163 -0.00360	
t[ps]: 3090.000 tot: 4883.137 de: 302.727 xc: 4580.410 un: 0.000) ze: -0.000 cb: 0.000 sf: 0.000 dm: 0.000 M: 0.00118 0.00160 -0.00360	
t[ps]: 3100.000 tot: 4883.136 de: 302.726 xc: 4580.410 un: 0.000) ze: -0.000 cb: 0.000 sf: 0.000 dm: 0.000 M: 0.00118 0.00158 -0.00360	
t[ps]: 3110.000 tot: 4883.134 de: 302.725 xc: 4580.410 un: 0.000) ze: -0.000 cb: 0.000 sf: 0.000 dm: 0.000 M: 0.00119 0.00156 -0.00360	
t[ps]: 3120.000 tot: 4883.133 de: 302.724 xc: 4580.409 un: 0.000) ze: -0.000 cb: 0.000 sf: 0.000 dm: 0.000 M: 0.00120 0.00154 -0.00360	
t[ps]: 3122.000 tot: 4883.133 de: 302.724 xc: 4580.409 un: 0.000) ze: -0.000 cb: 0.000 sf: 0.000 dm: 0.000 M: 0.00120 0.00154 -0.00360	
Simulation finished.		
simulation time: 00:05:51.505		
hertel@euclide:~/Docs/tetmag/example1\$		

4. Analyze the results





Importance of Advanced Mathematics and Numerics

Example: Calculation of dipolar magnetic field More 100.0 than two orders Massive reduction of numerical costs Original matrix by using H2-type hierarchichal matrices Matrix size in GB 10.0 of magnitude 100 -90 -Matrix compression [%] 99% matrix compression 80 -1.0 -- H2 70 -60 -H2-compressed matrix 50 -50000 100000 150000 200000 0 Boundary nodes 0.1 -Converting a problem of 1e+05 1e+04 3e+04 Complexity $\mathcal{O}(N^2)$ to $\mathcal{O}(N)$ Number of surface nodes Hertel et al., Efficient mathematical algorithms and numerical implementations can save J. Magn. Magn. Mater. large amounts of hardware resources and countless hours of CPU time 477, 118 (2019)

Part2: General remarks on scientific code development and best practices

Why publish your code?

- Service to the scientific community
- Reproducibility and transparence of published data
- Recognition of work done during (years of) code development
- Possible collaboration and code improvement by the community
- Removes necessity to protect the code against theft



Specific funding for scientific code development?